# A permuted factors approach for the linearization of polynomial matrices

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- (+) Reliable numerical algorithms are available for matrix pencils.
- (+) Special techniques exist for structured matrix pencils (symmetric, Hamiltonian etc.).

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- (+) P(s),  $\hat{P}(s)$  can be constructed by inspection of the coefficient matrices of T(s).
- (+) The matrices involved are relatively sparse.
- (-) In case the matrix T(s) exhibits symmetries, these are not reflected on P(s) and  $\hat{P}(s)$ .

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- The present work extends the permuted factors approach focusing on
  - The construction of (companion like) linearizations using the unperturbed coefficients of *T*(*s*).
  - Controlling certain aspects of the structure of the resulting pencils in order to preserve selected structural properties of the polynomial matrix.

### Definition (Elementary matrices)

Let T(s) a regular polynomial matrix. Then we define the following elementary matrices corresponding to T(s) as follows:

$$A_{k} = \begin{bmatrix} I_{p(k-1)} & 0 & \cdots \\ 0 & C_{k} & \ddots \\ \vdots & \ddots & I_{p(n-k-1)} \end{bmatrix}, \ k = 1, 2, \dots, n-1,$$

where

$$C_k = \left[ \begin{array}{cc} 0 & I_p \\ I_p & -T_k \end{array} \right]$$

and

$$A_0 = diag\{-T_0, I_{p(n-1)}\}.$$

#### Definition

Let  $\mathcal{I} = (i_1, i_2, \dots, i_m)$  be an ordered tuple containing indices from  $\{0, 1, 2, \dots, n-1\}$ . Then  $A_{\mathcal{I}} := A_{i_1}A_{i_2}\cdots A_{i_m}$ .

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#### Theorem

[Antoniou and Vologiannidis, 2004] Let  $i, j \in \{0, 1, 2, ..., n-1\}$ . Then  $A_iA_j = A_jA_i$  if and only if  $|i - j| \neq 1$ .

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Let  $\mathcal{I}_1$  and  $\mathcal{I}_2$  be two tuples.  $\mathcal{I}_1$  will be termed equivalent to  $\mathcal{I}_2$  ( $\mathcal{I}_1 \sim \mathcal{I}_2$ ) if and only if  $A_{\mathcal{I}_1} = A_{\mathcal{I}_2}$ .

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• We will use the following notation:

• Let  $k, l \in \mathbb{Z}$  with  $k \leq l$ . Then  $(k : l) := \begin{cases} (k, k+1, ..., l), k \leq l \\ \emptyset, k > l \end{cases}$ 

• 
$$A_{\varnothing} = I_{np}$$
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• If 
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A product of elementary matrices  $A_{\mathcal{I}}$  will be termed **operation free** iff the block elements of  $A_{\mathcal{I}}$  are either 0,  $I_p$  or  $-T_i$  (for generic matrices  $T_i$ ).

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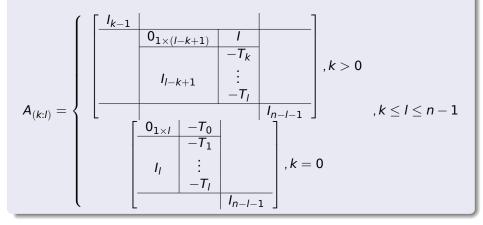
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#### Example

$$\begin{aligned} A_0 A_1 A_0 &= \begin{bmatrix} 0 & -T_0 \\ -T_0 & -T_1 \\ & & I_{p(n-2)} \end{bmatrix} \text{ is operation free,} \\ A_1 A_0 A_1 &= \begin{bmatrix} I_p & -T_1 \\ -T_1 & T_1^2 - T_0 \\ & & & I_{p(n-2)} \end{bmatrix} \text{ is not.} \end{aligned}$$

## Lemma (Range Product)

The product  $A_{(k:l)}$  is of the form



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A row standard form is  $(A_0)(A_1A_0)(A_2A_1A_0)(A_3A_2A_1A_0)$ .

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#### Theorem

Column and row standard forms are operation free.

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Let  $\mathcal{I} = (i_1, i_2, ..., i_k)$  be an index tuple.  $\mathcal{I}$  will be called successor infixed if and only if for every pair of indices  $i_a, i_b \in \mathcal{I}$ , with  $1 \le a < b \le k$ , satisfying  $i_a = i_b$ , there exists at least one index  $i_c = i_a + 1$ , such that a < c < b.

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- **(a)**  $A_{\mathcal{I}}$  can be written in a row standard form.

• We can arrive to similar results using inverses of elementary matrices i.e.

$$A_{-k} := A_k^{-1} = \begin{bmatrix} I_{p(k-1)} & 0 & \cdots \\ 0 & C_k^{-1} & \ddots \\ \vdots & \ddots & I_{p(n-k-1)} \end{bmatrix}, \ k = 1, \dots, n-1$$
$$C_{-k} := C_k^{-1} = \begin{bmatrix} T_k & I_p \\ I_p & 0 \end{bmatrix} \text{ and } A_{-n} = diag\{I_{p(n-1)}, T_n\}.$$

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# Example

$$(A_{-4}A_{-3}A_{-2}A_{-1})(A_{-4}A_{-3}A_{-2})(A_{-4}A_{-3})(A_{-4}) =$$

$$\begin{bmatrix} T_1 & T_2 & T_3 & T_4 \\ T_2 & T_3 & T_4 & 0 \\ T_3 & T_4 & 0 & 0 \\ T_4 & 0 & 0 & 0 \end{bmatrix}$$

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- Then the matrix pencil

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is a linearization of T(s) and its coefficients are operation free matrices.

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#### Lemma

A product  $A_{\mathcal{I}}$  is block symmetric if-f  $\mathcal{I} \sim \overline{\mathcal{I}}$ .

Image: A matrix

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- Choose  $k \in \{1, 2, ..., n\}$ .
- Let P be a permutation of the tuple (0 : k − 1) and L<sub>P</sub>, R<sub>P</sub> tuples with elements from (0 : k − 2) s.t. (L<sub>P</sub>, P, R<sub>P</sub>) satisfies the SIP.
- Let N be a permutation of the tuple (−n : −k) and L<sub>N</sub>, R<sub>N</sub> tuples with elements from (−n : −k − 1) s.t. (L<sub>N</sub>, N, R<sub>N</sub>) satisfies the SIP.
- Then the matrix pencil

$$\mathsf{sA}_{(\mathcal{L}_{\mathcal{N}},\mathcal{L}_{\mathcal{P}},\mathcal{N},\mathcal{R}_{\mathcal{P}},\mathcal{R}_{\mathcal{N}})} - \mathsf{A}_{(\mathcal{L}_{\mathcal{N}},\mathcal{L}_{\mathcal{P}},\mathcal{P},\mathcal{R}_{\mathcal{P}},\mathcal{R}_{\mathcal{N}})}$$

is a linearization of T(s) and its coefficients are operation free matrices.

#### Lemma

A product  $A_{\mathcal{I}}$  is block symmetric if-f  $\mathcal{I} \sim \overline{\mathcal{I}}$ .

• Notice that  $T_0$  is allowed to be singular if  $0 \notin (\mathcal{L}_{\mathcal{P}}, \mathcal{R}_{\mathcal{P}})$  while the same holds for  $T_n$  if  $-n \notin (\mathcal{L}_{\mathcal{N}}, \mathcal{R}_{\mathcal{N}})$ .

#### Corollary (Lancaster's symmetric linearizations)

The symmetric linearizations  $L_k(s) = sS_{k-1} - S_k$ , k = 1, ..., n of [Lancaster and Prells, 2007] can be produced ( $T_0$  and  $T_n$  must be nonsingular) by using the following sets to the previous theorem

$$\mathcal{P} = (\mathbf{0}: k-1), \mathcal{N}=(-n:-k),$$
  

$$\mathcal{R}_{\mathcal{P}} = ((\mathbf{0}: k-2), \dots, (\mathbf{0}: \mathbf{0})),$$
  

$$\mathcal{R}_{\mathcal{N}} = ((-n:-k-1), \dots, (-n:-n)),$$
  

$$\mathcal{L}_{\mathcal{P}} = \varnothing, \mathcal{L}_{\mathcal{N}} = \varnothing.$$

#### Corollary (Lancaster's symmetric linearizations)

The symmetric linearizations  $L_k(s) = sS_{k-1} - S_k$ , k = 1, ..., n of [Lancaster and Prells, 2007] can be produced ( $T_0$  and  $T_n$  must be nonsingular) by using the following sets to the previous theorem

$$\mathcal{P} = (0:k-1), \mathcal{N} = (-n:-k), \mathcal{R}_{\mathcal{P}} = ((0:k-2), \dots, (0:0)), \mathcal{R}_{\mathcal{N}} = ((-n:-k-1), \dots, (-n:-n)), \mathcal{L}_{\mathcal{P}} = \emptyset, \mathcal{L}_{\mathcal{N}} = \emptyset.$$

# Example $(L_3(s))$

Using 
$$k = 3$$
,  $\mathcal{P} = (0, 1, 2)$ ,  $\mathcal{N} = (-5, -4, -3)$ ,  $\mathcal{R}_{\mathcal{P}} = (0, 1, 0)$ ,  
 $\mathcal{R}_{\mathcal{N}} = (-5, -4, -5)$ ,  $\mathcal{L}_{\mathcal{P}} = \mathcal{L}_{\mathcal{N}} = \emptyset$ .

$$L_{3}(s) = s \begin{bmatrix} 0 & -T_{0} & 0 & 0 & 0 \\ -T_{0} & -T_{1} & 0 & 0 & 0 \\ 0 & 0 & T_{3} & T_{4} & T_{5} \\ 0 & 0 & T_{4} & T_{5} & 0 \\ 0 & 0 & T_{5} & 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 & -T_{0} & 0 & 0 \\ 0 & -T_{0} & -T_{1} & 0 & 0 \\ -T_{0} & -T_{1} & -T_{2} & 0 & 0 \\ 0 & 0 & 0 & T_{4} & T_{5} \\ 0 & 0 & 0 & T_{5} & 0 \end{bmatrix}.$$

## Example (Lancaster's modified $L_3(s)$ )

Using k = 3 and  $\mathcal{P} = (1, 2, 0)$ ,  $\mathcal{N} = (-5, -3, -4)$ ,  $\mathcal{R}_{\mathcal{P}} = (1)$ ,  $\mathcal{L}_{\mathcal{N}} = (-4)$ ,  $\mathcal{L}_{\mathcal{P}} = \mathcal{R}_{\mathcal{N}} = \emptyset$ 

$$L_{3}^{'}(s) = s \begin{bmatrix} 0 & l & 0 & 0 & 0 \\ l & -T_{1} & 0 & 0 & 0 \\ 0 & 0 & T_{3} & T_{4} & l \\ 0 & 0 & T_{4} & T_{5} & 0 \\ 0 & 0 & l & 0 & 0 \end{bmatrix} - \begin{bmatrix} 0 & 0 & l & 0 & 0 \\ 0 & -T_{0} & -T_{1} & 0 & 0 \\ l & -T_{1} & -T_{2} & 0 & 0 \\ 0 & 0 & 0 & T_{4} & l \\ 0 & 0 & 0 & l & 0 \end{bmatrix}.$$

Notice that  $T_0$  and  $T_n$  can be singular.

• A new family of linearizations has been given.

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- The members of the new family are operation free.
- Particular members can be constructed according to requirements dictated by the structure of the polynomial matrix.

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